Unified models for Mixing Fluids

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Unified Models for Mixing Fluids

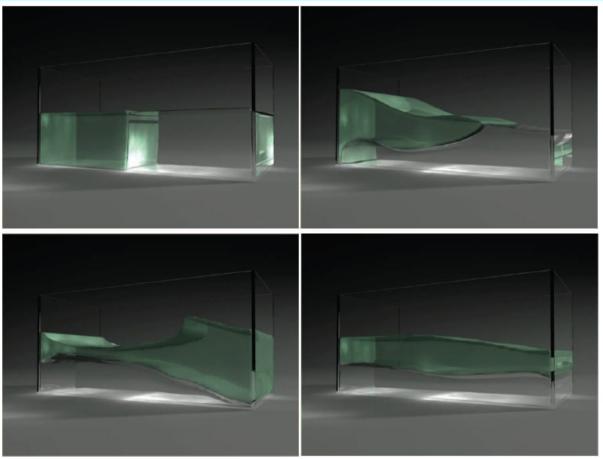
- Large density interface problems in fluids:
 - drop formation
 - puddles on surface
 - separation of dissimilar fluids
- We will look at 2 different solutions for this problem







A Unified Handling of Immiscible and Miscible Fluids



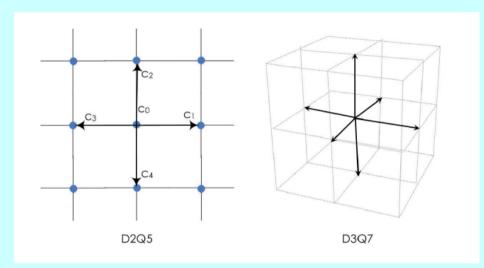
CASA

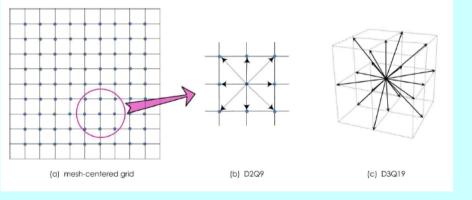
Jinho Park, Younghwi Kim, Daehyeon Wi, Nahyup Kang, Sung Yong Shin, Junyong Noh Korea Advanced Institute of Science and Technology

A Unified Handling of Immiscible and Miscible Fluids

- Uses chemical potential energy formulations to alter time-varying concentration fields
- The concentration fields determine the interfaces
- Uses Lattice Boltzmann method

What is the Lattice Boltzmann Method?



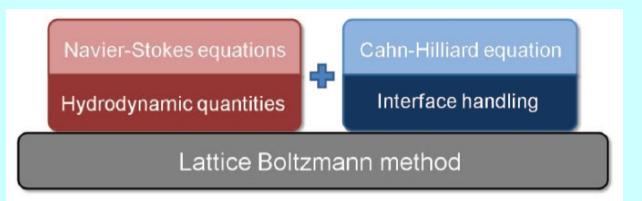


- Simulates a Newtonian fluid with collision models (A Newtonian fluid flows no matter how fast it is stirred, i.e. water, not pudding)
- Simulated particles move between neighboring nodes of a discrete lattice
- "the viscous flow behavior emerges automatically from the intrinsic particle streaming and collision processes" -- Wikipedia

Why use the Lattice Boltzmann Method?

- Local dynamics (like SPH) reduce computation
- Easy to model multiphase models by modifying the collision process
- No need for ad-hoc reinitialization of particles or creation of fictitious particles (as in level-set methods)
- Easy to adapt for parallelization

 Use the Lattice Boltzmann method to solve both C-H & N-S eqns



- Concentration Field with normalized values [0,1] represents how much of a substance exists in the space
 - .5 is high potential
 - 0,1 are low potential
- The isosurface represents interface between fluids

$$\{\mathbf{x} \, | \, e(\mathbf{x}, t) \, = \, 0.5\}$$

- Concentration field evolution is governed by the Cahn-Hilliard equation
- Models steady decrease of free energy of miscibility
- In other words: segregation of separate fluids over time
- Free energy

$$\mathcal{F}(\mathcal{C}) = \int_{\Omega} \left[B(\mathcal{C}) + I(\mathcal{C}) \right] d\mathbf{x},$$

• Interfacial energy

$$I = \frac{1}{2}\kappa |\nabla c(\mathbf{x},t)|^2$$

• Bulk energy (zero for miscible fluids)

$$B = c^2(1 - c)^2$$
.

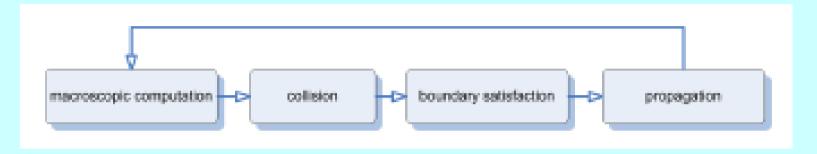
C-H equation for N fluids

$$rac{D\mathcal{C}}{Dt} = M riangle \Upsilon,$$

 $\Upsilon = (\mu_1, \mu_2, \dots, \mu_n)$
 $\mu_i = rac{dx}{dx_i} = rac{dH}{dx_i} - \kappa_i riangle \alpha_i$

- Need to solve (N-1) C-H eqns for N fluids
- For surface tension, they multiply chemical potential by concentration and sum over all the fluids

$$\sum_{i} \mu_i \nabla \alpha_i$$



- LBM computation process is as follows:
- Macroscopic computation (density, velocity, and concentration are calculated from distribution functions)
- Collision (Bhatnagar-Gross-Krook method)
- Boundary condition satisfaction
- Propagation (move to neighboring nodes)
- Repeat for next time step...

Results



Contributions

- Unified handling of multiple miscible and immiscible fluids
- Guaranteed conservation of concentration
- Handles fluids with very low viscosity
- Easily & massively parallelizable

Density Contrast SPH Interfaces



SCA

B. Solenthaler and R. Pajarola Visualization and MultiMedia Lab University of Zurich, Switzerland

What is Smoothed Particle Hydrodynamics?

- A Lagrangian method (mesh-free) where information moves with particles, not through a grid
- Particles have smoothing length which defines their neighborhood
- Their properties are smoothed over this length using a kernel function (cubic spline or Gaussian)
- Properties are summed based on properties of particles in neighborhood
- Sum is weighted by distance and density and kernel function

What is Smoothed Particle Hydrodynamics?

• Basic SPH equation for any property A

$$A(\mathbf{r}) = \sum_{j} \frac{m_j}{\rho_j} A_j W(\mathbf{r} - \mathbf{r}_j, h),$$

• Example of using it for density

$$\rho_i = \sum_j m_j W(\mathbf{r}_{ij}, h)$$

- For fluid simulation using Navier-Stokes eqns we want to find pressure and viscosity fields
- Gradient example

$$\nabla A(\mathbf{r}) = \sum_{j} m_j \frac{A_j}{\rho_j} \nabla W(|\mathbf{r} - \mathbf{r}_j|, h).$$

What is Smoothed Particle Hydrodynamics?

$$p_i = \frac{k\rho_0}{\gamma}((\frac{\rho_i}{\rho_0})^{\gamma} - 1)$$

• Pressure Force

$$\mathbf{F}_{i}^{pressure} = -\frac{m_{i}}{\rho_{i}} \sum_{j} \frac{m_{j}}{\rho_{j}} \frac{p_{i} + p_{j}}{2} \nabla W(\mathbf{r}_{ij}, h)$$

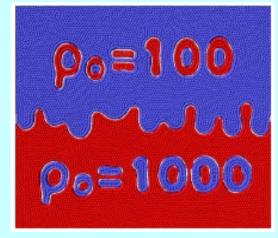
• Viscosity Force

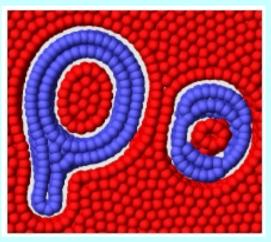
$$\mathbf{F}_{i}^{viscosity} = \frac{m_{i}}{\rho_{i}} \sum_{j} \frac{\mu_{i} + \mu_{j}}{2} \frac{m_{j}}{\rho_{j}} (\mathbf{v}_{j} - \mathbf{v}_{i}) \nabla^{2} W(\mathbf{r}_{ij}, h),$$

What is Smoothed Particle Hydrodynamics?

- Pros
 - Conservation of mass for free
 - Lends itself to adaptivity by changing smoothing length locally (based on density)
 - Implicitly models fine detail (droplets)
- Cons
 - Adaptivity can only be based on density b/c it is Lagrangian in nature
 - Mesh generation

Problems with standard SPH

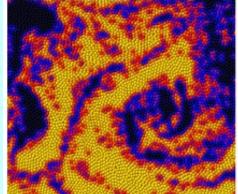




- Rest densities and masses of neighboring particles that vary within the smoothing length can cause:
 - unphysical density/pressure variations
 - unnatural interface tensions
 - numerical instabilities

Problems with standard SPH

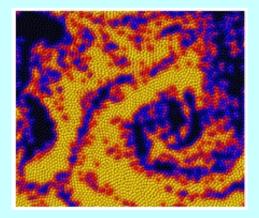
- Standard density summation is a problem when neighbors have different rest densities (and thus different masses)
- Close to interface, particle density is over/under-estimated (smoothed)

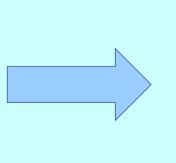


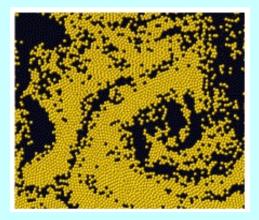
Standard SPH Density

- Bad densities lead to false pressure which in turn leads to wrong interface tension which creates a large gap at interface (or worse -- instability)
- Numerical instabilities occur when density ratios > 10 exist (smaller time steps don't help)

- Compute density based on particle number density
- Derive new formulas for pressure, pressure forces, and viscous forces
- Add a new interface tension model







Solution to standard SPH problems:

New Particle Density

 $\delta_i = \sum_j W(\mathbf{r}_{ij}, h).$ (each particle assumes neighbors have same rest density & mass as themselves)

Adapted Density

$$\rho_i = \sum_j m_j W(\mathbf{r}_{ij}, h)$$

$$\rho_i = m_i \delta_i = m_i \sum_j W(\mathbf{r}_{ij}, h)$$

Adpated Volume

$$V_i = \frac{m_i}{\tilde{p}_i} = \frac{1}{\delta_i}.$$

Solution to standard SPH problems:

Adapted Pressure

$$p_i = \frac{k\rho_0}{\gamma} ((\frac{\rho_i}{\rho_0})^{\gamma} - 1) \qquad \qquad \tilde{p}_i = \frac{k\rho_0}{\gamma} ((\frac{\tilde{\rho}_i}{\rho_0})^{\gamma} - 1)$$

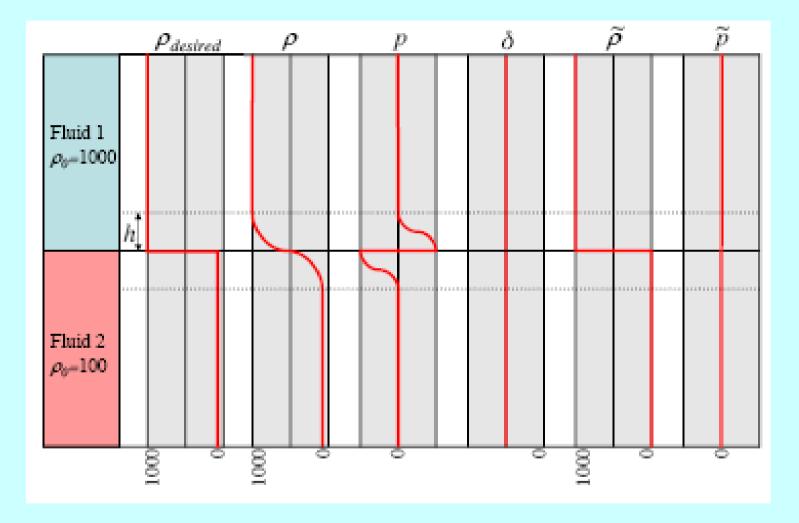
Pressure Gradient Term

• Pressure Force

Viscous Forces

$$\mathbf{F}_{i}^{viscosity} = \frac{m_{i}}{\rho_{i}} \sum_{j} \frac{\mu_{i} + \mu_{j}}{2} \frac{m_{j}}{\rho_{j}} (\mathbf{v}_{j} - \mathbf{v}_{i}) \nabla^{2} W(\mathbf{r}_{ij}, h),$$

$$\mathbf{F}_{i}^{viscosity} = \frac{1}{\delta_{i}} \sum_{j} \frac{\mu_{i} + \mu_{j}}{2} \frac{1}{\delta_{j}} (\mathbf{v}_{j} - \mathbf{v}_{i}) \nabla^{2} W(\mathbf{r}_{ij}, h).$$



New Interface Tension Model

• Interface Tension force

$$\mathbf{F}^{interface} = \frac{1}{\delta_i} \boldsymbol{\sigma} \boldsymbol{\kappa} \mathbf{n}$$

- Define a colorfield (non-zero at each particle position) to compute curvature and normals
- Smoothed, normalized colorfield

$$< c >_i = \frac{\sum_j \frac{1}{\delta_j} c_j W(\mathbf{r}_{ij}, h)}{\sum_j \frac{1}{\delta_j} W(\mathbf{r}_{ij}, h)}$$

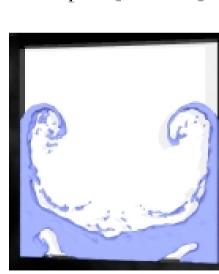
• SPH formulations of normal and curvature using the colorfield

$$\mathbf{n}_i = \sum_j \frac{1}{\delta_j} (< c >_j - < c >_i) \nabla W(\mathbf{r}_{ij}, h).$$

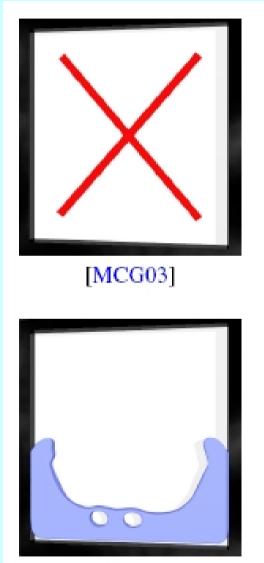
$$\kappa = \frac{-\sum_{j} \frac{1}{\delta_{j}} (\hat{\mathbf{n}}_{j} - \hat{\mathbf{n}}_{i}) \cdot \nabla W(\mathbf{r}_{ij}, h)}{\sum_{j} \frac{1}{\delta_{j}} W(\mathbf{r}_{ij}, h)}$$

Results





adapted [Mon92]



[Mon92]

Contributions

- Unified handling of multiple miscible and immiscible fluids
- Solves physically incorrect interface problems inherent in basic SPH
- Solves numerical instability problems
- ... and does so without increasing computational costs
- User can select desired amount of interface tension