

Ray Tracing Implicit Surfaces

Overview

- Similar to **CSG**
 - Combine primitive objects to form complex object
- Primitives are “density fields”
- Combine by summing densities
- The surface is all points at which the density equals a user-defined threshold

Implicit Surface

- A surface not explicitly represented
- The surface consists of all points which satisfy a function

$$F(x,y,z) = 0$$

- Usually, the implicit function is defined so that

$$F(x,y,z) < 0 \Rightarrow \text{inside the object}$$

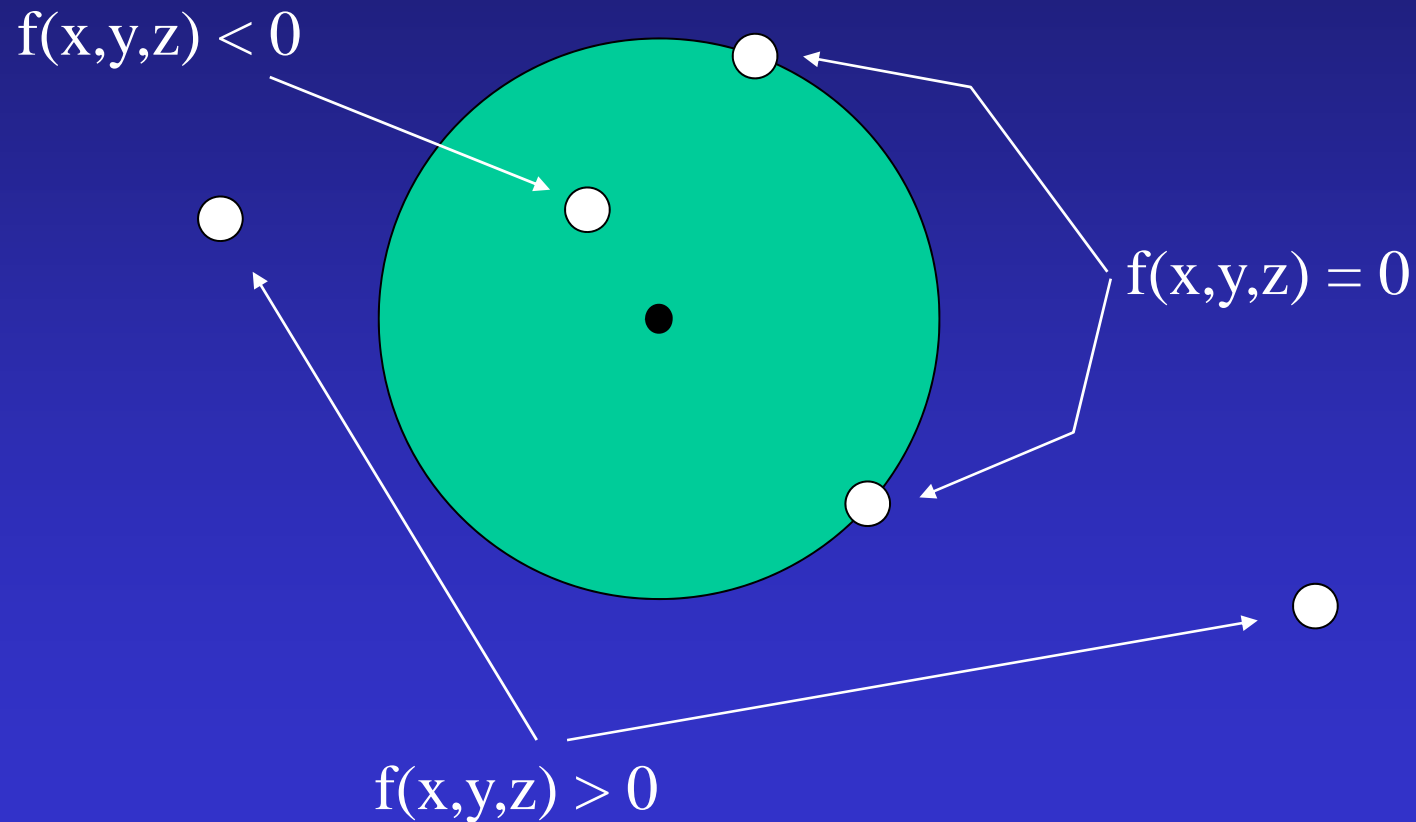
$$F(x,y,z) > 0 \Rightarrow \text{outside the surface}$$

Sometimes $F(x,y,z)$ is based on a distance-to-a-central-element

- The surface points have to be searched for!

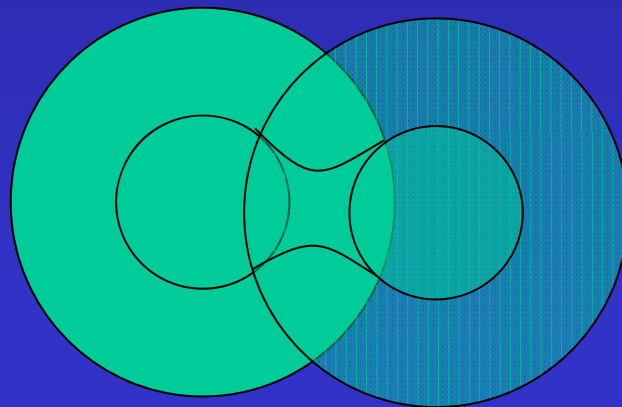
For example: single metaball

$$F(x,y,z) = x^2 + y^2 + z^2 - r^2$$



Multiple Implicits

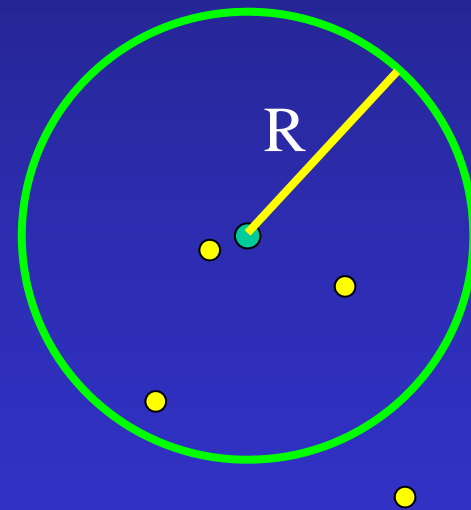
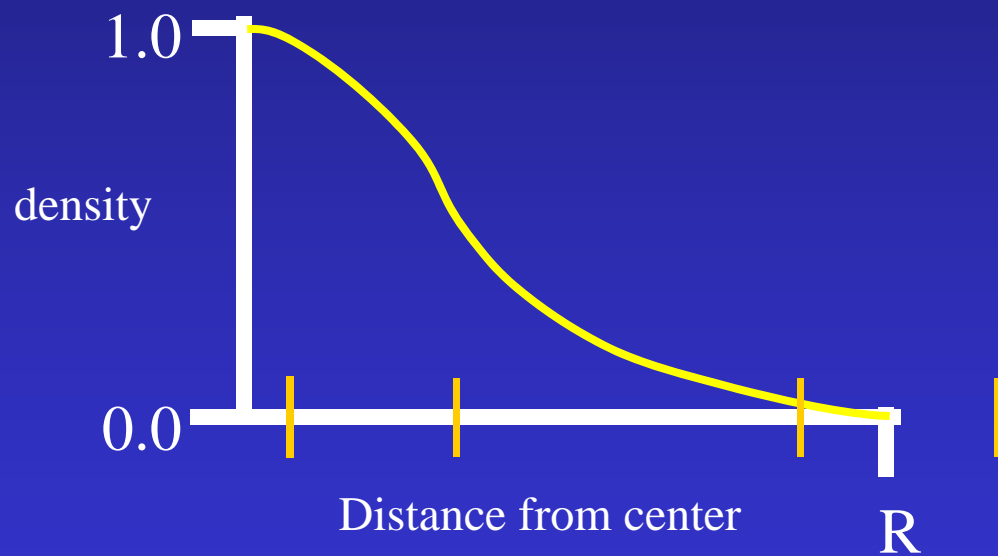
- Define each primitive as positive density field
- Sum densities
- Surface is defined at threshold
- Usually have finite radius of influence



Organic shapes

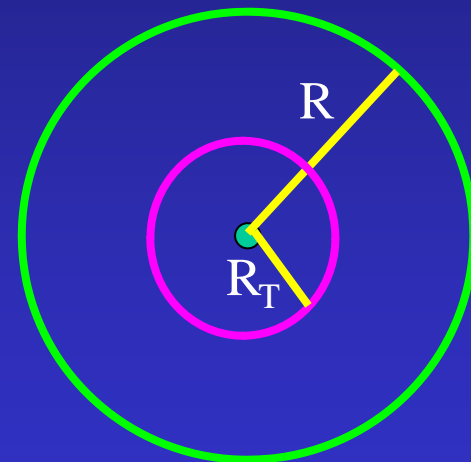
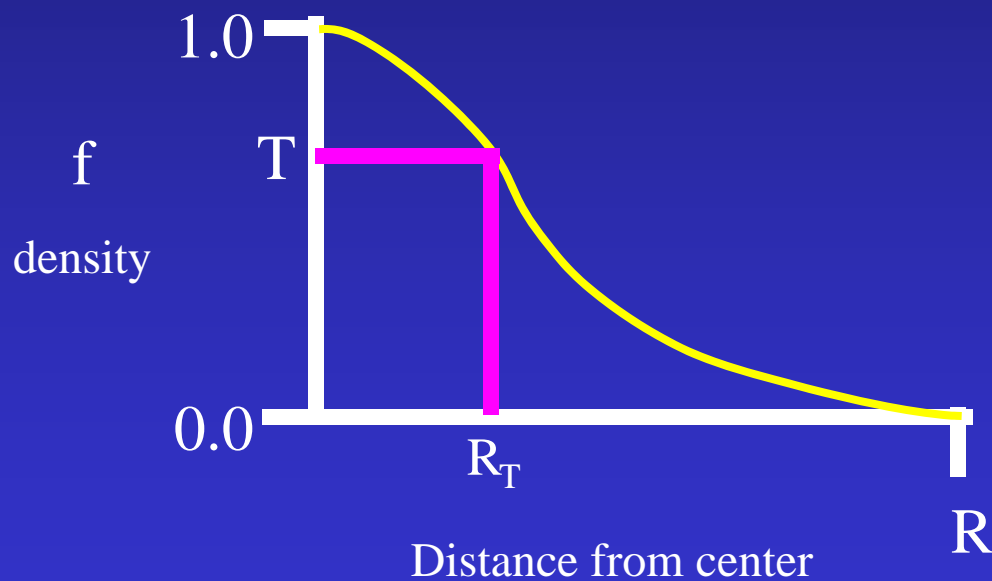


Density Function



Threshold

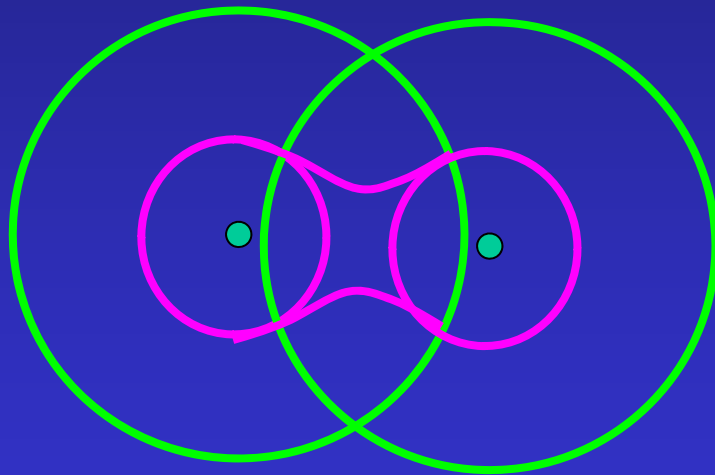
- Define threshold that defines density of surface
- R_T is the radius of the isosurface (blob) in isolation



$$\{p | f(p) - T = 0\}$$

Blended Blobs

- Define surface as sum of densities



$$\{p | \sum f_i(p) - T = 0\}$$

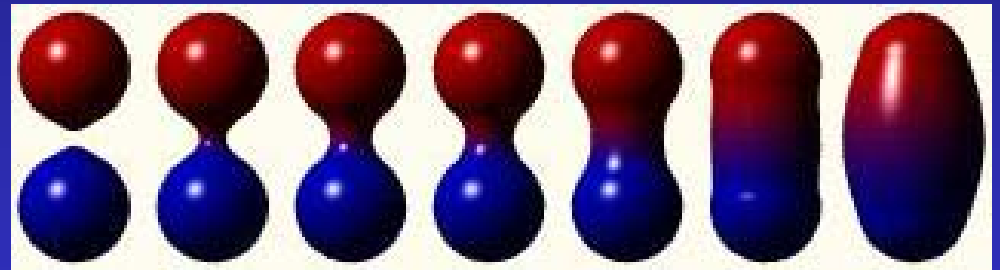
$$\{p | \sum w_i f_i(p) - T = 0\}$$

Weighted Density Functions

- Define surface as weighted sum of densities

$$F(p) = \sum w_i f_i(p) - T = 0$$

To keep the same radius,
but increase blending,
change weight, w_i , and the
threshold, T ,
simultaneously.

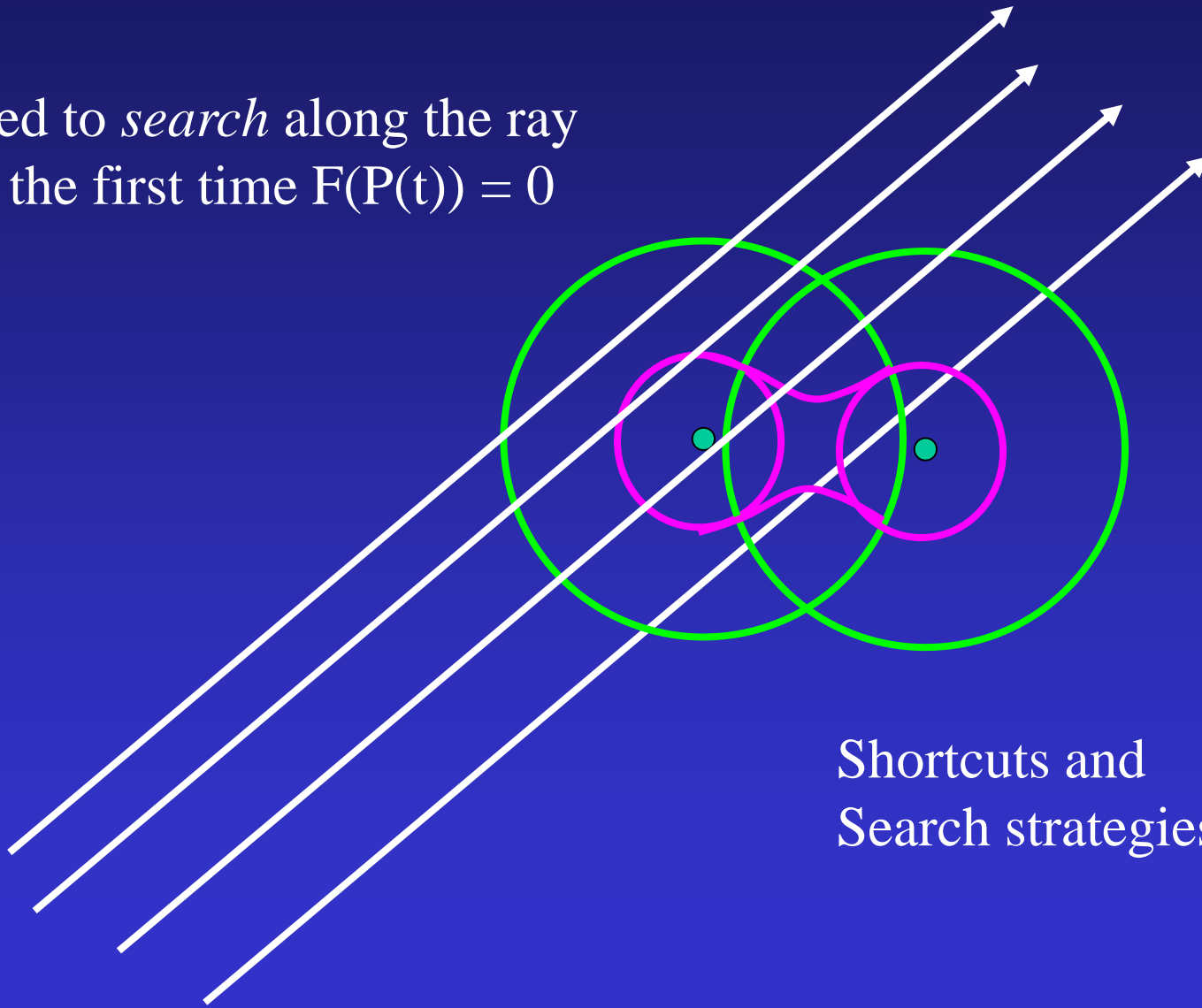


Weights can be negative, too!



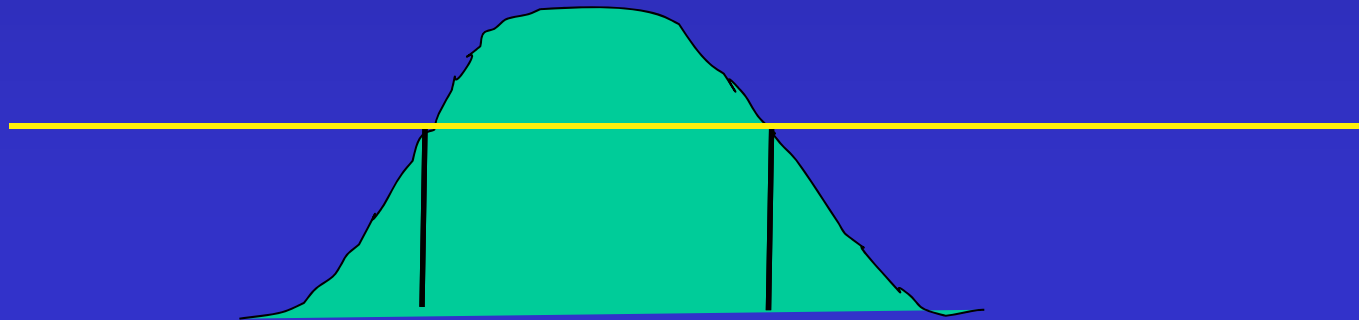
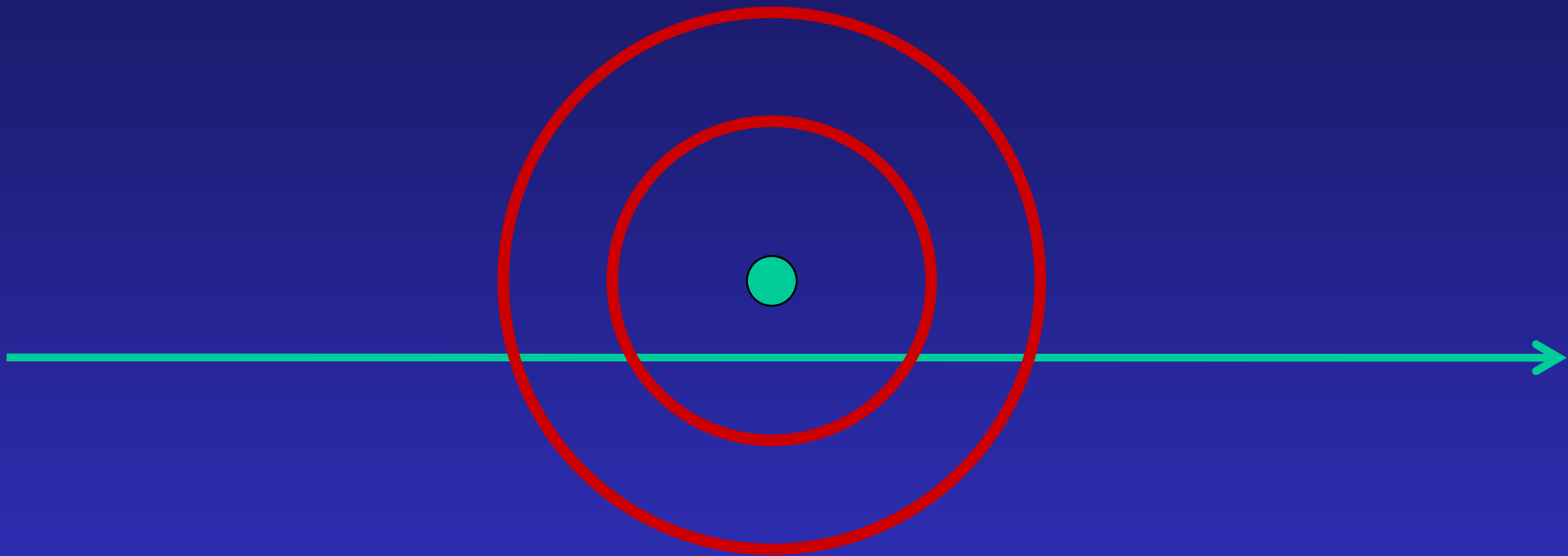
Ray Intersection

Need to *search* along the ray
for the first time $F(P(t)) = 0$



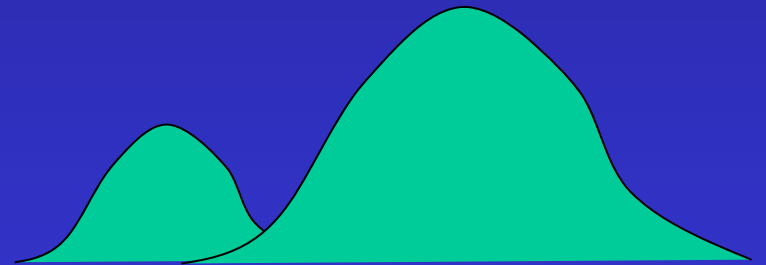
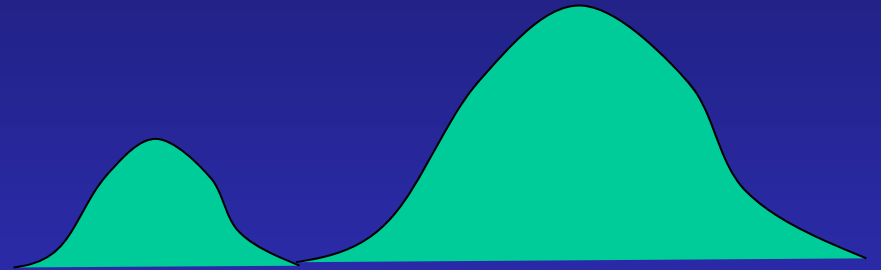
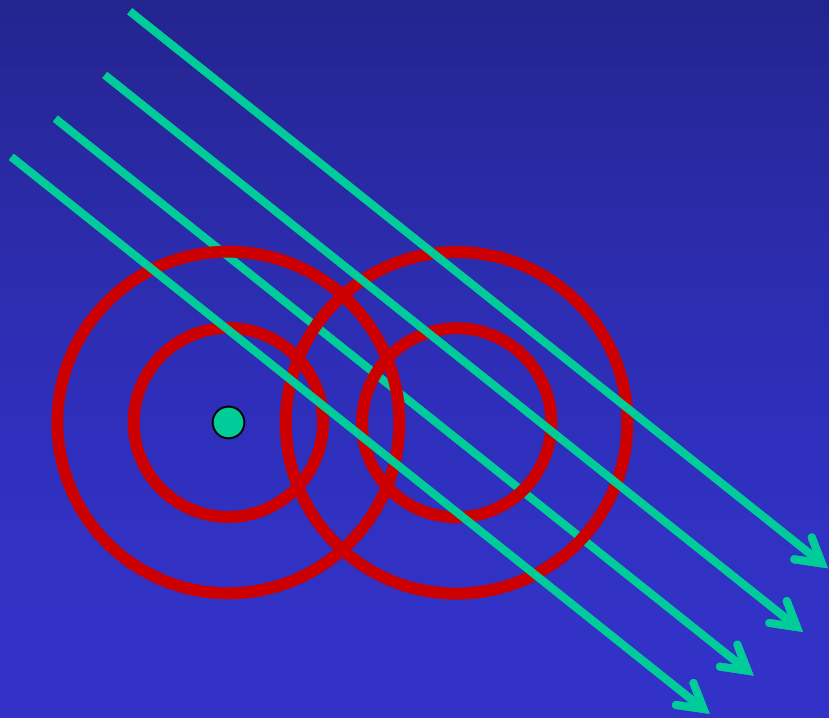
Shortcuts and
Search strategies?

Search for Intersection



Search for Intersection

Identify spans of interest: bounds on intersection



Density Functions

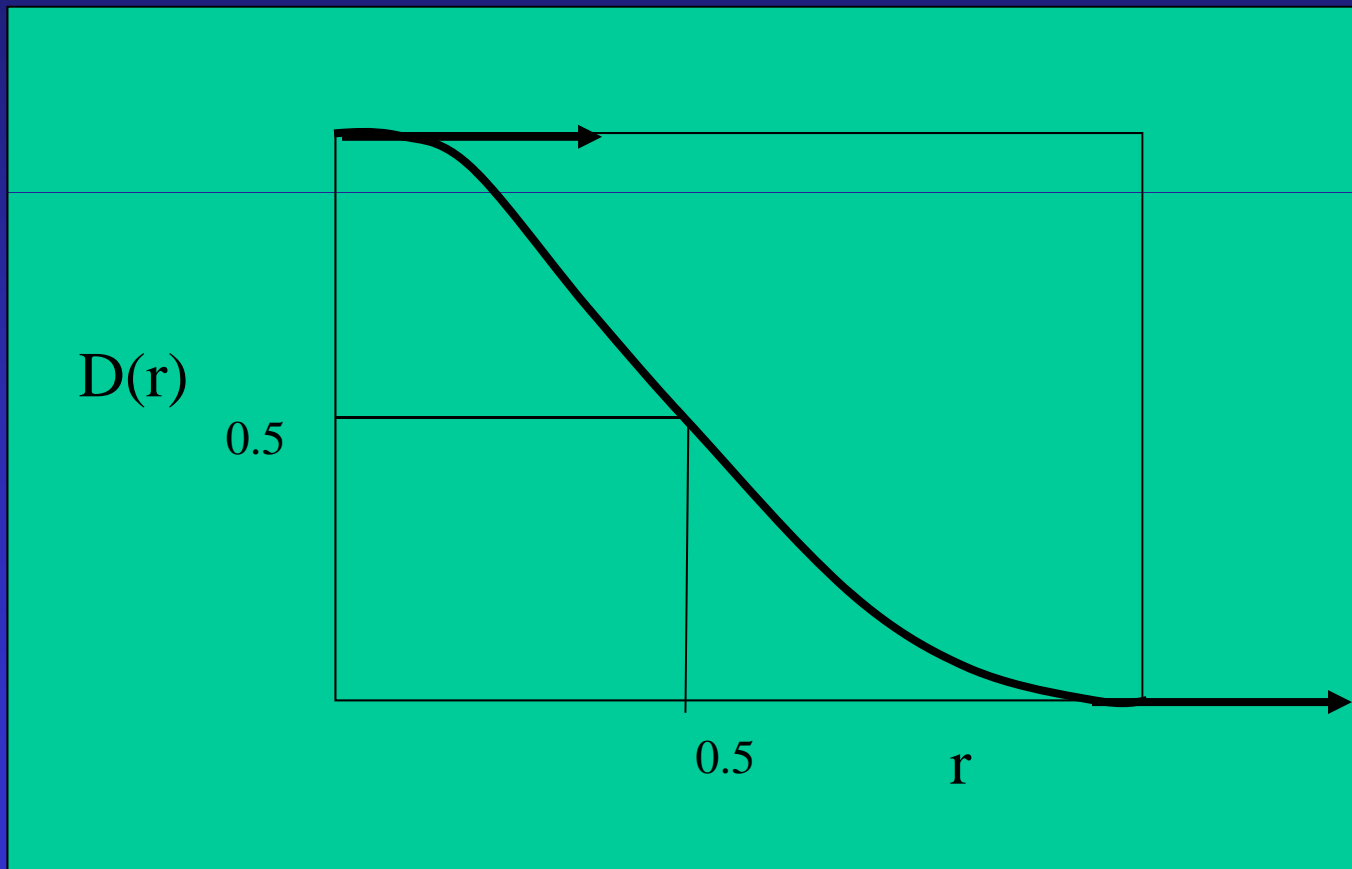
Define a density function that is:

- Easy to evaluate
- Blends smoothly
- Intuitive to use

Density functions proposed in the literature

- Exponential
- Piecewise cubic
- Cubic in distance squared

Density Functions



Distance-based Density Functions

$$f_i(p) = D(|P-C_i|/R) = D(r)$$

r is normalized distance

$$D_1(r) = (1-r^2)^3 \quad 0 \leq r < 1$$

$$D_2(r) = 1 - (4/9)r^6 + (17/9)r^4 - (22/9)r^2 \quad 0 \leq r < 1$$

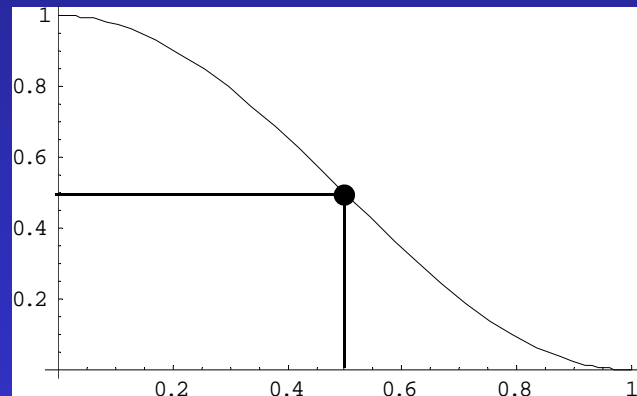
$$D_3(r) = \exp(-ar^2)$$

$$D_4(r) = 1-3r^2 \quad 0 \leq r < 1/3$$

$$(3/2)(1-r)^2 \quad 1/3 \leq r < 1$$

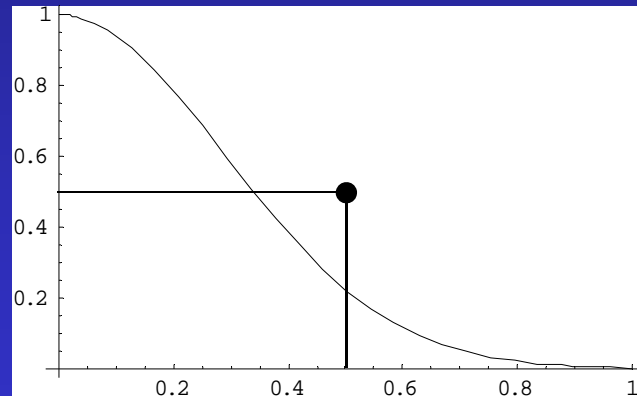
Distance-based Density Functions

$$D_2(r) = 1 - (4/9)r^6 + (17/9)r^4 - (22/9)r^2 \quad 0 \leq r < 1$$



Distance-based Density Functions

$$D_3(r) = \exp(-ar^2)$$



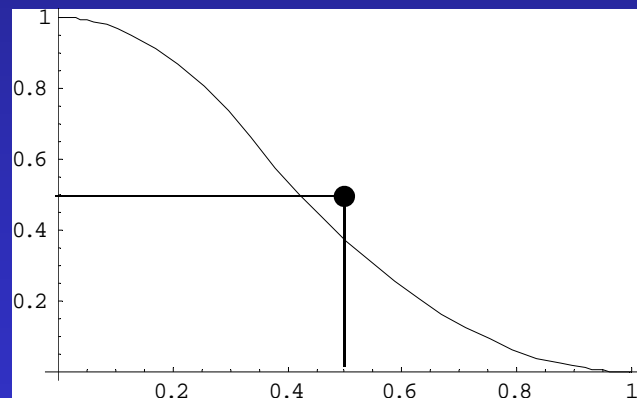
Distance-based Density Functions

$$D_4(r) = 1 - 3r^2$$

$$0 \leq r < 1/3$$

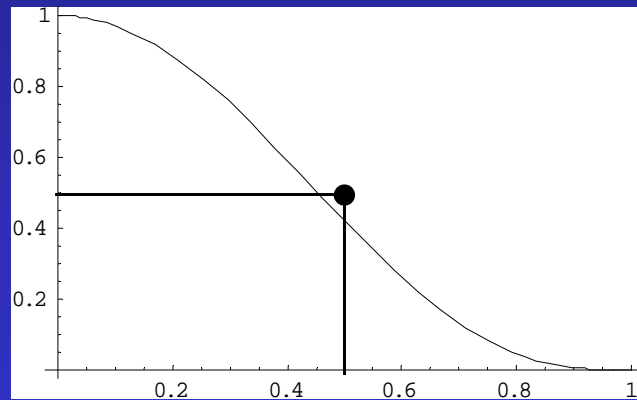
$$(3/2)(1-r)^2$$

$$1/3 \leq r < 1$$



Distance-based Density Functions

$$D_1(r) = (1-r^2)^3 \quad 0 \leq r < 1$$



Distance-based Primitives

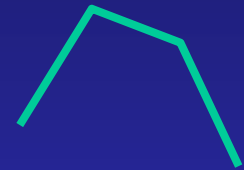
Point



Line



Polyline



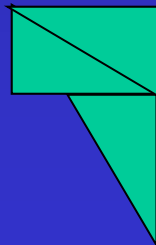
Polygon



Polyhedron



Polygonal mesh



Anything you can
efficiently compute the
distance from

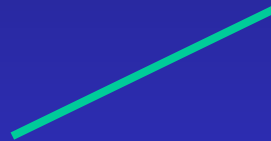
Distance-based Primitives

Point



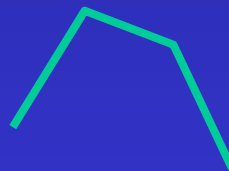
Distance from point

Line



Distance from
line or endpoints
- partition by
perpendiculars

Polyline



Distance from
one of lines or
points - partition
by perpendiculars

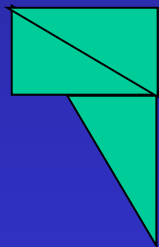
Distance-based Primitives

Polygon



Partition space by planes perpendicular to plane through an edge

Polygonal mesh



Same, for each face - two planes per edge

Distance-based Primitives

Polyhedra



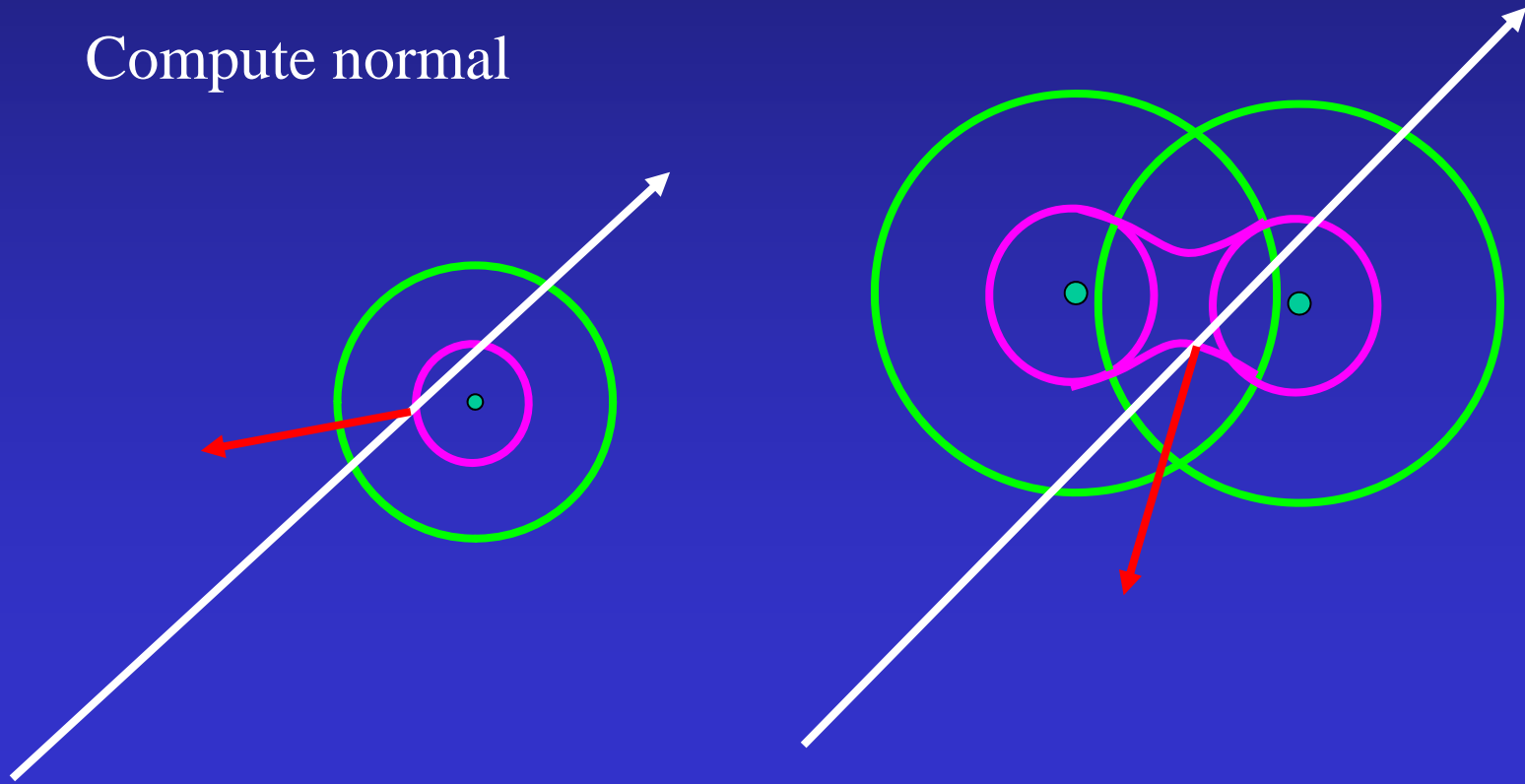
Convex?

Concave?

Display Considerations

Find point of intersection along ray: $F(P(t)) = 0$

Compute normal



Computing the Normal

Form analytic expression of implicit function

And take partial derivatives

$$\mathbf{N} = (\delta F / \delta x, \delta F / \delta y, \delta F / \delta z)$$

Take discrete approximation by sampling function

Compute gradient

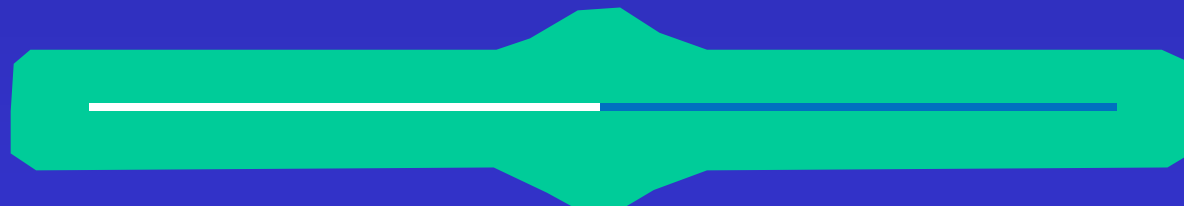
$$\mathbf{N} = (F(x+dx,y,z)-F(x,y,z), F(x,y +dy,z)-F(x,y,z), F(x,y,z +dz)-F(x,y,z))$$

Bulge problem

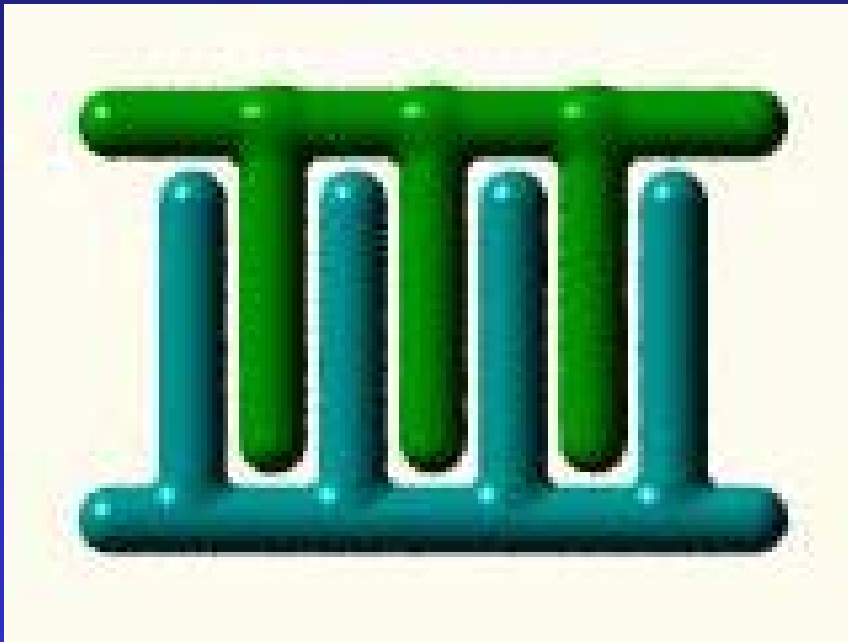
One long primitive



Two side-by-side primitives



CSG-approach to control blending



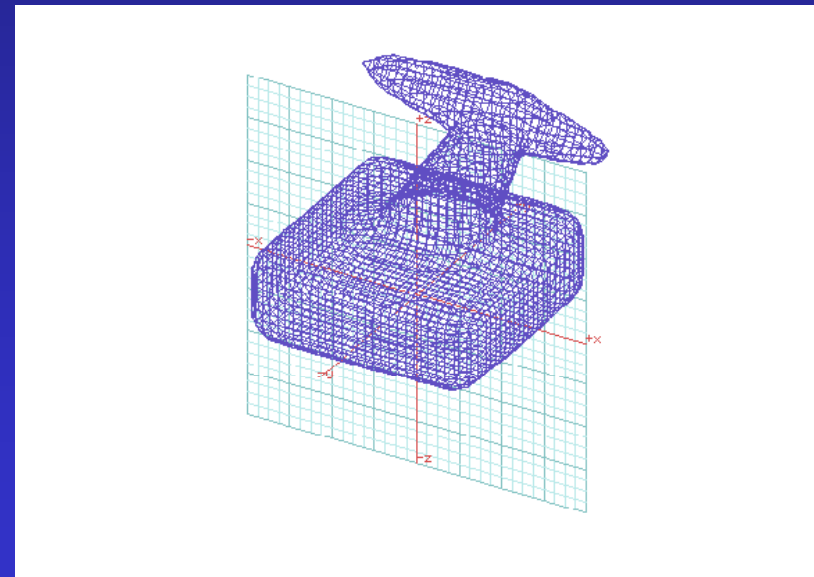
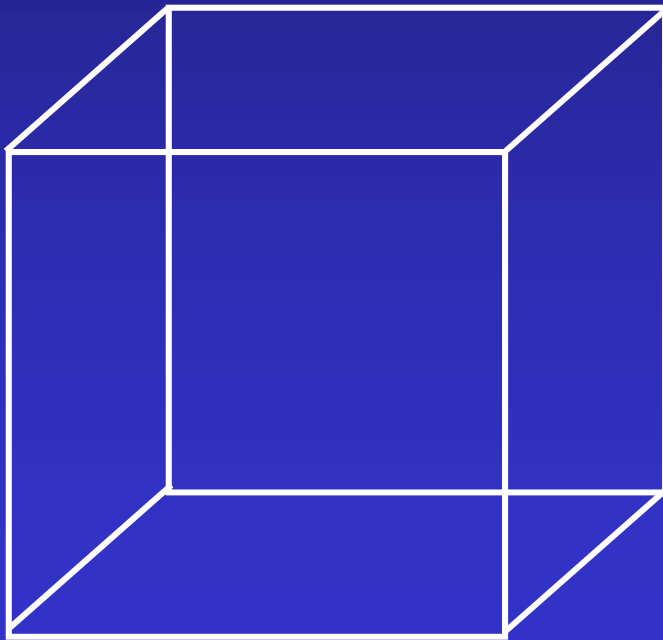
Use nodes to combine primitives by either summing or taking max of functions

Complexity

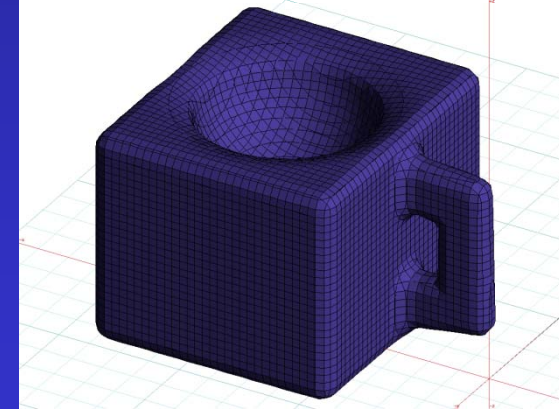
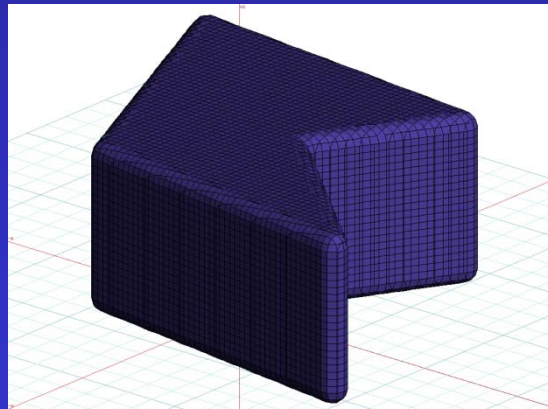
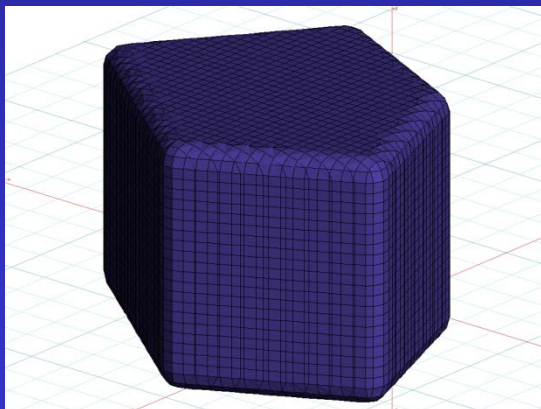
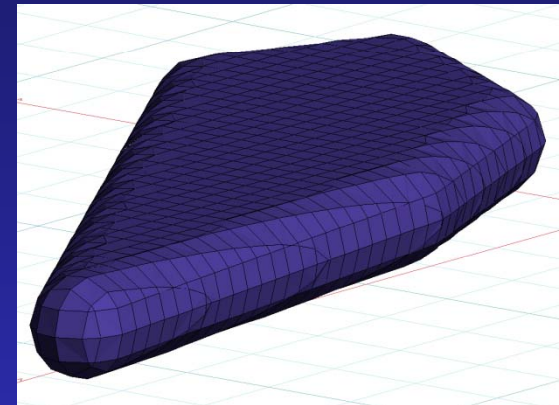
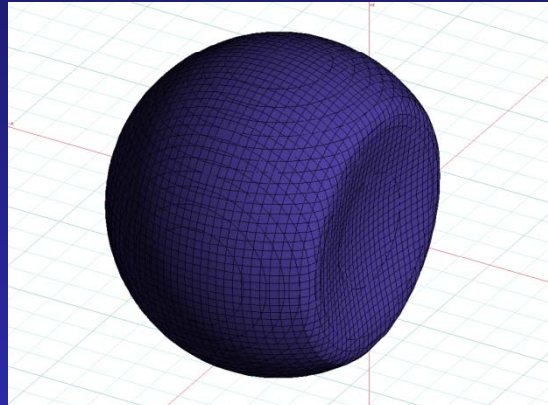
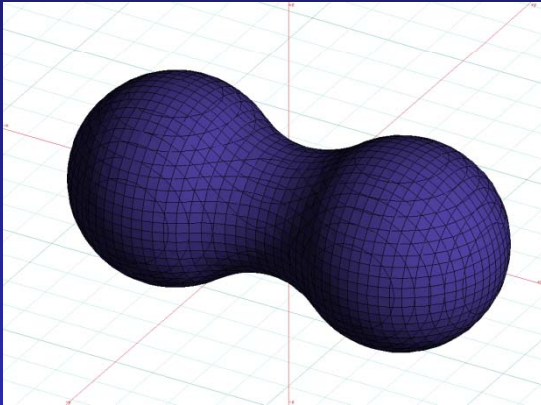
- Bounding volumes
- Spatial subdivision - cellular bucket sort
- Hierarchical spatial subdivision – quadtree
- Binary spatial partitioning

Display alternative

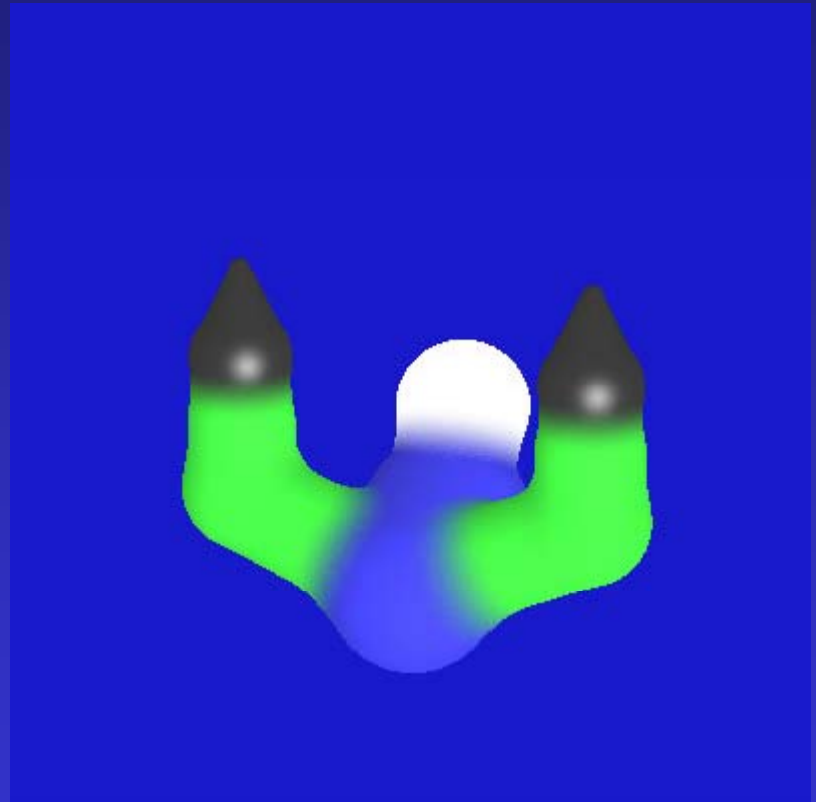
Marching cubes algorithm - construct surface fragments from isosurface intersections with grid cells



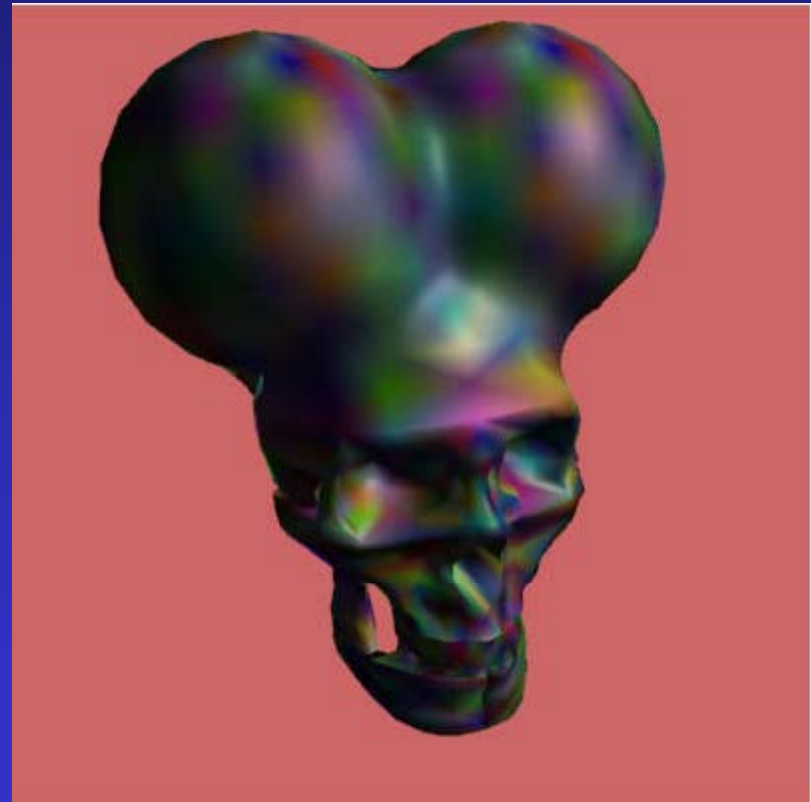
Distance-based Primitives



Examples



Examples



Examples

