

## Lecture #27

## Separate Compilation

- Would like to have in our program the line:  
JSR Sqrt  
where "Sqrt" is a label in a *different* program!
  - Aside 1: what does your current assembler do with such a thing?
  - Aside 2: Sqrt must still be on the same page as the JSR instruction!
- We extend our language and provide a (typical) mechanism for resolving this...

## New Pseudo Op: EXT

1. `.EXT symbol_name`
  - "external"
  - indicates that `symbol_name` is defined in a different program
  - legal to use, but assembler can't fill it in

```
Prog .ORIG
      .EXT      Sqrt
      JSR       Sqrt
      TRAP x25
      .END
```

## New Pseudo Op: ENT

2. `.ENT symbol_name`
  - `symbol_name` is defined in *this* program
  - it is a *global* symbol
  - i.e., may be referenced in other programs
- These pseudo ops change the "scope" of a symbol
  - local (default) -----> global (with `.ENT`)
- Q: why not make global the default, or make them all global?

## Example: Two Programs

```
Main .ORIG
      .EXT Sqrt
      ...
      JSR Sqrt
      ...
      .END
```

```
Subr .ORIG
      .ENT Sqrt
      ...
Sqrt ST R1, Tmp1
      ...
      RET
Tmp1 .BLKW #1
      .END
```

- These two programs can now be:
  - independently written
  - independently assembled into 2 object files
- How does the *linkage* between these object files get resolved?

So now back to loaders...

## Binary Symbolic Subroutine Loaders (BSS)

- One of the first relocating loaders
  - 1956: IBM, GE, UNIVAC
- Allows multiple program segments (“control sections” in your textbook)
  - different languages
  - different times

} Separate compilation!
- Let’s examine each of the “tasks” in turn...

## Tasks for BSS Loader

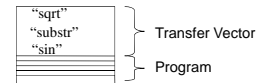
- Allocation
  - assembler calculates each segment length
  - loader adds them all up
  - load location obtained from OS
- Relocation
  - assembler flags words for relocation (bit masks)
  - loader makes modifications

## Tasks for BSS Loader II

- Linking
  - by loader (with help from assembler)
  - a restricted form
  - uses a “transfer vector”
- Loading
  - by loader

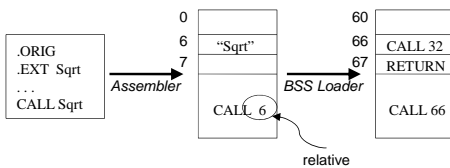
## Transfer Vector

- Contains 1 entry / external symbol used by this program segment
- Assembler sets aside room at the beginning of the object file for TV
- Assembler places symbolic representation of referenced external symbols in TV



## Transfer Vector II

- All calls to external symbols are replaced with calls to appropriate locations in TV
- Loader replaces the entries in TV with calls to the appropriate location



## Example

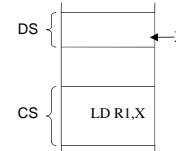
<pre> Prog  .ORIG       .EXT Sqrt, Print Soln  .BLKW #1 main  LD   R1,=#16       JSR  Sqrt       ST   R2,Soln       LD   R1,Soln       JSR  Print       TRAP x25       .END  main                     </pre>	<pre> 0000  3C04       48A5       2C04       D000       0000 000A  5555       2211       4800       340A       220A       4805       F025       0010                     </pre>	<pre> 0005  3C09       48C0       2C09       D000       0000                     </pre>	<pre> BProg 00000012 V0000 Sqrt V0005 Print T000B 2211M9 T000C 4800M9 T000D 340AM9 T000E 220AM9 T000F 4805M9 T0010 F025 T0011 0010 E000B                     </pre>
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## Disadvantages of Transfer Vector

- Overhead
  - time (extra call instruction)
  - space (for transfer vector in object file)
- Works for subroutine calls, but what about for sharing *data*?
  - e.g., LD R1,XValue
  - this cannot be replaced with a call to TV, or even a load from the TV

## Data Sharing with BSS Loaders

- Permit 1 common (shared) “data segment”
- All external data is in this one data segment

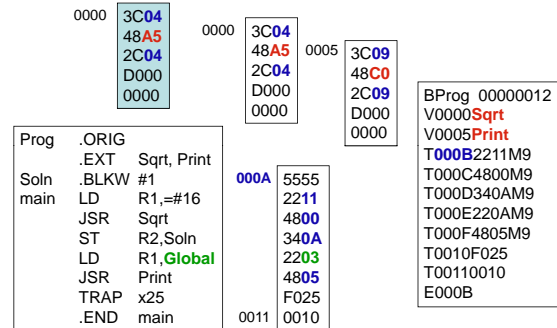


- Assembler replaces X with its (relative) address in the data segment

## Impact on Relocation

- What does this mean for relocating the program?
  - relative to the LL of data segment, and relative to the LL of the control segment
- There are now 2 different kinds of “relative”!
  - relative to the LL of data segment, and relative to the LL of the control segment
- Assembler must distinguish between them
  - extend relocation information
  - e.g., use 2 bits per word
    - 00 - absolute
    - 01 - relative (to CS load location)
    - 10 - relative (to DS load location)

## Example



Lecture #28

Direct Linking Loaders

## Introduction

- General linking/loading strategy
- Very common in modern systems
- And used in Lab #3!
- Advantages:
  - separate assembly
  - multiple control *and* data segments
  - lower time overhead (in program execution)
  - lower space overhead (in program's object file)

## Assembler Responsibilities

1. Header information
  - length of segment
  - execution start address
2. List of entry points
  - those defined in this segment
  - gives their (relative) value
3. List of external references
  - used in this segment
  - defined outside of segment

## Assembler Responsibilities II

4. Relocation information
    - modification records
  5. Machine code
    - text records
- There are some new things here, which suggests defining some new record types...

## Entry Record

- Similar to BSS loader
- List and define all the entry points
- Possible format:
  - `<Flag> <symbol_name> <value>`
- Examples:
  - ESqrt 0008 (since symbols are <= 6 characters)
  - ESqrt=0008
- Idea: provide information to loader

## For Lab #3

- We'll adopt the following conventions:
  - the program name is always (implicitly) an entry point
  - entry point symbols must be relative
    - (if you wish to handle absolute too, that's up to you)

## External Record

- Can be combined with text and modification records if you wish
- Examples:
  - .FILL x3202 T301F3202
  - ST R1,Num T301F3202M9
  - ST R1,Enum T301F3200X9Enum
- Format:
  - T <addr> <machine\_code> X
  - <symbol\_name>

## External Records II

- Such a record tells the loader to:
  - find CS that defines that (external) symbol
  - find the value of that symbol within that CS (i.e., look at the corresponding entry record!)
  - add the low 9 bits of the value to the text record
  - add the load location of the CS *that defines the symbol* to the text record
    - this last step is just like the usual "relocation operation" of relative symbols, but using the LL of segment that defines the symbol

## Lecture #29

## Direct Linking Loaders: Algorithm and Data Structures

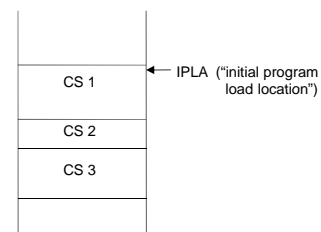
## Algorithm & Data Structures

- Problem is similar to assembler:
  - resolve symbols (with forward references)
  - use these values
- Solution is similar too!
  - use \_\_\_\_\_
- Pass #1: find definition of all external symbols
- Pass #2: relocate, link, load

## Pass #1

- Q. What does the assembler tell the loader about each ENT symbol?
- A.
- So, to determine the *actual* symbol value, loader must calculate:  
\_\_\_\_\_ + \_\_\_\_\_
- For lab #3, we can load each segment into one contiguous block of memory

## Loaded Memory



## Pass #1: Pseudocode

```
calculate total size (all segments)
get IPLA (from OS)
for each segment do:
    calculate PLA
    add entry symbols to "external symbol
                        table" (EST)
    if symbol already present
        flag an error
rof
```

## Example

Main	.ORIG		Lib	.ORIG	
	.EXT	Put		.EXT	Num
	.ENT	Num		.ENT	Put
	JMP	Put	Put	LD	R0,Num
Num	.FILL	#7		TRAP	x31
	.END			TRAP	x25
				.END	

## External Symbol Table

- For our example:

Name	Value	R/A
------	-------	-----
- (assume: IPLA = \_\_\_\_\_ )
- Note: for lab #3, can restrict external symbols to be relative only

## Pass #2: Pseudocode

```
set IPLA
for each CS
    save PLA of this CS
    for each text record in CS
        calculate memory location
        relocate record: absolute -
                        relative -
                        external -
        load the word
rof
rof
transfer control to "start" of first segment
```

- Recommended exercise: link and load our example (assuming IPLA of \_\_\_\_\_ )

## Checking External Symbols

- Q. When do we check whether an external symbol is actually defined?
- A.
- Option #1: during / after pass 1
  - keep a list of symbols seen in external records
  - after pass 1, check this list against EST

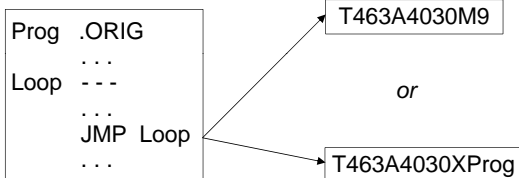
## Checking External Symbols II

- Option #2: during pass 2
  - we *know*:
    - external symbols used  $\subseteq$  EXT symbols declared
  - read in the records generated from EXT declarations
  - check symbols in these against the EST
- Option #3: during pass 2
  - when each text record is processed, report an error if the symbol is not in the EST

## Unifying “X” and “M”

- Don't really need 2 separate mechanisms!
- Recall meanings of
  - T \_\_\_\_\_ M
  - T \_\_\_\_\_ XSym
    - “Sym” is in EST
    - *add* this value of “Sym” to address field
- Recall that *segment names* always in EST
- This suggests that X can be seen as a more general form of M!

## Replacing “M” with “X”



## Linking with Libraries

- Common func's often defined in *libraries*
- Library linking can be made implicit:
  - after pass 1, may still have “unresolved external symbols” in EST
  - if so, search libraries for matching definitions and load them (after pass 1)
  - still some unresolved externals? Then error
- Typically, user-specified libraries searched first, then standard ones (automatically)

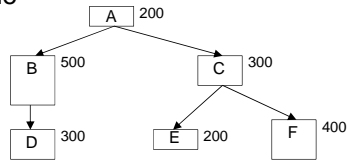
## Loader Refinements and Optimizations

## Problem: Space

- Consider a program that calls “sqrt”, “rnd”, and “substr”
- Each defined in its own (large) library
- So, linked and loaded program is *huge*
- Solutions (for saving memory):
  - virtual memory and paging
  - dynamic loading
  - dynamic linking

## Dynamic Loading

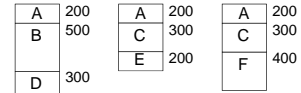
- Observe: program does 1 thing at a time  
∴ don't need all segments present simultaneously
- Example



Total Size = 1.9 Mb

## Dynamic Loading - Overlays

- B/D never together with C/E/F
- Define an "overlay structure" for how segments can be swapped in and out
- 3 scenarios:



Total Size =

1000

700

900

- Only 1Mb needed (length of longest path)
- Trade-off: memory space & performance

## Dynamic Linking

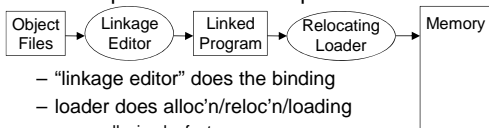
- Instead of branching directly to an external symbol, program issues a call request to OS
  - subroutine name is parameter for request
- OS responsibilities
  - keep table of loaded libraries
    - loads new library if needed
    - manages swapping of libraries as appropriate
  - transfer control to appropriate subroutine
  - return control to original program

## Dynamic Linking II

- "Binding": the association of an actual address (x6E5E) with a symbolic name ("Sqrt")
- Dynamic linking delays binding from *load* time to *execution* time ("late binding")
- Advantages:
  - many programs can share 1 loaded library
  - library can be recompiled on-the-fly
  - library only loaded if actually used

## Problem: Time

- Every time we want to execute a program, must re-link, relocate and re-load
  - costly if object code hasn't changed
- Idea: separate these two operations



- "linkage editor" does the binding
- loader does alloc'n/reloc'n/loading
  - small, simple, fast